What is claimed is:

1. A method for controlling an output quantity of a drive unit of a vehicle for at least a first operating state of said vehicle, the method comprising the steps of:

adjusting a desired value for said output quantity to a target value in dependence upon at least a request of a motor-specific component or a vehicle-specific component;

adjusting said target value in dependence upon that a driver command, which is inputted at an operator-controlled element, reaches said target value in a first operating state or in a second operating state different from said first operating state; and,

likewise increasing said desired value for said output quantity up to reaching said target value with an increase of said driver command inputted at said operator-controlled element.

2. The method of claim 1, wherein the desired value is maintained when there is a drop of said driver command inputted at said operator-controlled element.

3. The method of claim 1, wherein a motor rpm is selected as said output quantity.

4. The method of claim 1, wherein a torque is selected as said output quantity.

5. The method of claim 1, wherein a power is selected as said output quantity.

6. The method of claim 1, wherein an idle state is selected as said first operating state.

7. An arrangement for controlling an output quantity of a drive unit of a vehicle for at least a first operating state of said vehicle, the arrangement comprising:

means for adjusting a desired value for said output quantity to a target value in dependence upon at least a request of a motor-specific component or a vehicle-specific component;

said means functioning to adjust said target value in dependence upon that a driver command, which is inputted at an operator-controlled element, reaches said target value in a first operating state or in a second operating state different from said first operating state; and,

said means being adapted to likewise increase said desired value for said output quantity up to reaching said target value with an increase of said driver command inputted at an operator-controlled element.